

Day 1

Theory

- **Resistor:** Limits current. $V=IR$ $V=IR$
- **Capacitor:** Stores charge. Used for filtering/timing.
- **Diode:** One-way current. LED emits light.
- **Transistor:** Acts as a switch/amplifier (BJT: Base, Collector, Emitter).

Practical

- **Identify:** Use color codes (resistors), markings (caps, diodes)
- **Test:**
 - *Resistor:* Multimeter (Ω mode)
 - *Capacitor:* Capacitance mode
 - *Diode:* Diode mode (0.6–0.7V forward)
 - *Transistor:* Test junctions like two diodes



Circuit Laws (Ohm's & Kirchhoff's)

Theory:

- **Ohm's Law:** $V=IR$
- **KCL:** Sum of currents at a node = 0
- **KVL:** Sum of voltages in a loop = 0

Practical:

- **Simulation:** Use Proteus/Multisim to build circuits, measure voltages/currents.
- **Real Circuit:** Use breadboard, resistors, DC supply, and multimeter to verify laws.



Day 3

Semiconductor Basics

Theory

- Diode: Allows current in one direction.
- BJT: Current-controlled switch (NPN/PNP).
- MOSFET: Voltage-controlled switch (n/p-channel).

Practical

- Diode Test: Forward = $\sim 0.7V$, Reverse = OL.
- BJT Test: Check B-E and B-C like diodes.
- MOSFET Test: Check G-D, G-S isolation; D-S after charging gate.

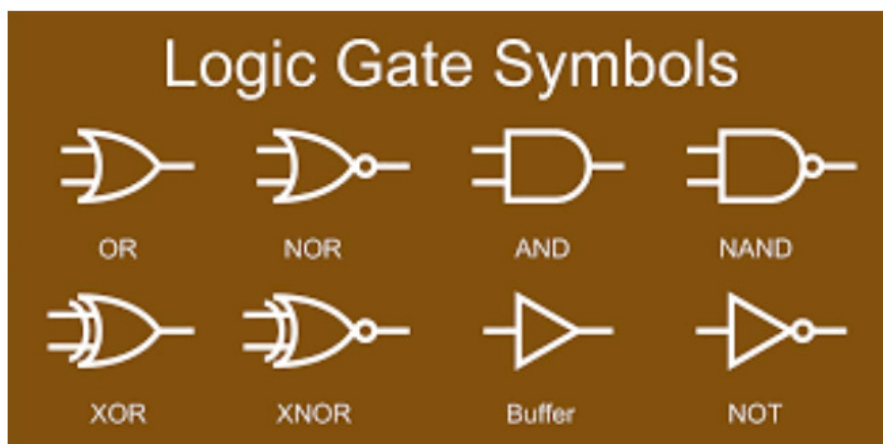
Day 4

Logic Gates

- AND: Output 1 if both inputs 1.
- OR: Output 1 if any input 1.
- NOT: Inverts input.
- NAND/NOR: Opposites of AND/OR.

Practical

- Simulate in TinkerCAD.
- Build with ICs on breadboard.



Day 5

Soldering & PCB Basics

Theory

- PCB Design Workflow:
 1. Create schematic (circuit diagram)
 2. Design PCB layout
 3. Generate Gerber files
 4. Send for fabrication

Practical

- Soldering:
 - Practice soldering components on perf board or sample PCB
 - Focus on clean joints, proper heating, and safety
- Design Tools:
 - KiCad / Eagle: Used to create schematics and PCB layouts
 - Demo: Place components, route traces, export files



Day 6

Arduino / Raspberry Pi Intro

Practical: Blink LED

- Arduino:
 - Program pin 13 to blink an LED (C/C++ in Arduino IDE).
 - Code: Turn pin HIGH for 1s, then LOW for 1s.
- Raspberry Pi:
 - Use GPIO pins to blink an LED (Python with RPi.GPIO library).
 - Code: Set GPIO pin, turn HIGH/LOW with delays.



Sensor Interfacing

Practical Projects

- **LDR (Light Sensor):**
 - Varies resistance with light; use in auto-light systems.
- **Ultrasonic Sensor:**
 - Measures distance using echo time (e.g., obstacle detection).
- **IR Sensor:**
 - Detects objects or motion; used in line-following robots.

Day 8

Motor Control

Practical

- . DC Motor:
 - Controlled via L293D H-bridge.
 - Use Arduino to set direction and speed (PWM).
- . Servo Motor:
 - Controlled with PWM signal (0–180° rotation).
 - Signal sent from Arduino pin.



Day 9

Wireless Communication (IoT)

Practical Applications

- ESP8266 (Wi-Fi):
 - Enables internet connectivity for Arduino.
 - Common use: Send sensor data to a web server or cloud.
 - Can create a local web page to monitor/control devices.
- Bluetooth (HC-05 / ESP32):
 - Allows wireless communication with smartphones.
 - Used for controlling LEDs, motors, etc., via mobile apps (e.g., Bluetooth Terminal, MIT App Inventor).



Day 11

Theory

- Rectifiers:
 - Convert AC to DC.
 - Types: Half-wave, full-wave, bridge.
- SMPS (Switch Mode Power Supply):
 - Efficient DC conversion using high-frequency switching.
 - Used in chargers, power adapters.

Demo

- Show rectifier output using diodes + filter capacitor.
- SMPS module demo with input/output voltage check.

Day 12

IoT & Industry 4.0

Concept

- IoT: Connects devices to share data via the internet.
- Industry 4.0: Combines IoT, automation, and cloud for smart systems.

Case Study: Cloud Data Logging

- Platforms: ThingSpeak, Blynk
- Flow: Sensor → ESP8266/ESP32 → Wi-Fi → Cloud
- Use: Real-time data monitoring (e.g., temperature, light)

Applications

- Smart farming
- Factory monitoring
- Home automation

Day 13

PCB Fabrication & Troubleshooting

Activities

- Lab Visit (if available):
 - Observe PCB manufacturing process: etching, drilling, masking.
- Soldering Practice:
 - Hands-on with components on a PCB.
 - Focus on clean joints, avoiding bridges.

Troubleshooting

- Check for:
 - Loose connections
 - Solder bridges
 - Component orientation
 - Continuity with multimeter